

# DSC 40B

## *Theoretical Foundations II*

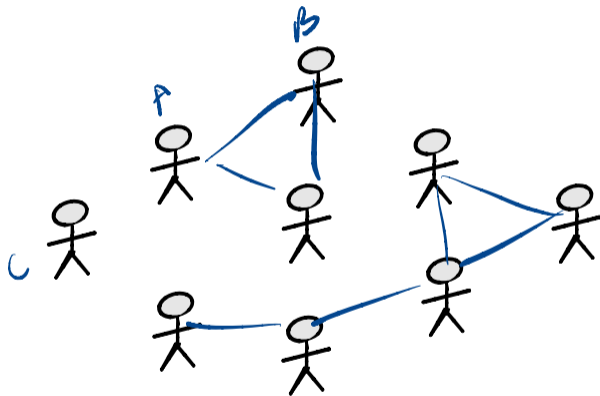
Lecture 10 | Part 1

### **Graphs**

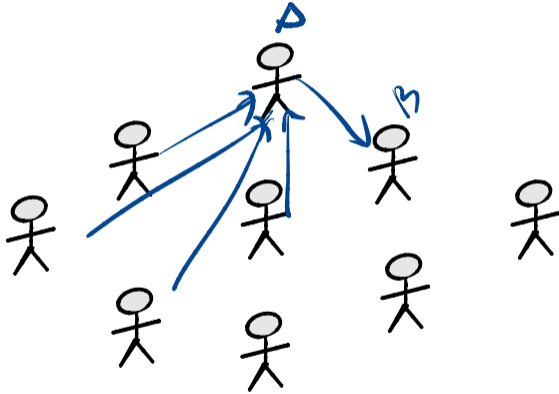
# Data Types

- ▶ **Feature vectors**
  - ▶ We care about attributes of individuals.
- ▶ **Graphs**
  - ▶ We care about relationships between individuals.

# Example: Facebook



# Example: Twitter



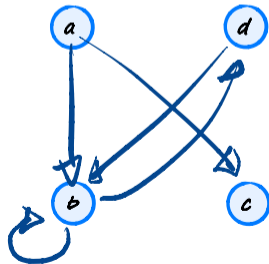
tuple  $(a,c) \neq (c,a)$

## Definition

A **directed graph** (or **digraph**)  $G$  is a pair  $(V, E)$  <sup>tuple</sup> where  $V$  is a finite set of **nodes** (or **vertices**) and  $E$  is a set of ordered pairs (the **edges**).

**Example:**

$V = \{a, b, c, d\}$   
 $E = \{(a, c), (a, b), (d, b), (b, d), (b, b)\}$



self-loop

# Directed Graphs (More Formally)

$E$  is a subset of the **Cartesian product**,  $V \times V$ .

**Example:**


$$\{a, b, c\} \times \{1, 2\} = \{ (a, 1), (a, 2), (b, 1), (b, 2), (c, 1), (c, 2) \}$$

$$V = \{a, b, c\}$$

$$V \times V = \{(a,a), (a,b), \dots, (b,a), \dots\}$$

## Consequences

Because the edge set of a directed graph is allowed to be *any* subset of  $V \times V$ :

- ✓ the edges have directions.
  - ▶ e.g.,  $(a, b)$  is “from  $a$  to  $b$ ”
- ▶ can have “opposite” edges.
  - ▶ e.g.,  $(a, b)$  and  $(b, a)$ .
- ▶ can have “self-loops”
  - ▶ e.g.,  $(a, a)$  

$\{a, c\} = \{c, a\}$

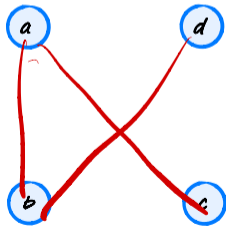
## Definition

An **undirected graph**  $G$  is a pair  $(V, E)$  where  $V$  is a finite set of **nodes** (or **vertices**) and  $E$  is a set of unordered, distinct pairs (the **edges**).

$\{a, a\}$

**Example:**

$$V = \{a, b, c, d\}$$
$$E = \{\{a, c\}, \{a, b\}, \{d, b\}\}$$





# Undirected Graphs (More Formally)

An edge in an undirected graph is a set  $\{u, v\}$  where  $u \neq v$ . This has consequences:

- ▶ the edges have **no direction**.
  - ▶ e.g.,  $\{a, b\}$  is **not** “from”  $a$  “to”  $b$ .
- ▶ **cannot** have “opposite” edges.
  - ▶ e.g.,  $\{a, b\}$  and  $\{b, a\}$  are the same.
- ▶ **cannot** have “self-loops”
  - ▶ e.g.,  $\{a, a\}$  is not a valid edge

## Notational Note

Although edges in undirected graphs are sets, we typically write them as pairs:  $(u, v)$  instead of  $\{u, v\}$ .

# Summary

- ▶ Edges have direction:
  - ▶ Directed: **yes**
  - ▶ Undirected: **no**
- ▶ Self-loops,  $(u, u)$ ?
  - ▶ Directed: **yes**
  - ▶ Undirected: **no**
- ▶ Opposite edges,  $(u, v)$  and  $(v, u)$ ?
  - ▶ Directed: **yes**
  - ▶ Undirected: **no** (they are the same edge)



## Note

Neither directed nor undirected graphs can have **duplicate edges**<sup>1</sup>

---

<sup>1</sup>There are other definitions which allow duplicate edges.

## Note

$$E \subseteq V \times V$$

$\neq$

Graphs don't need to be "connected"<sup>2</sup>

a

d



$$G = (V, \emptyset)$$

b

c

---

<sup>2</sup>There are other definitions which allow duplicate edges.

## Exercise

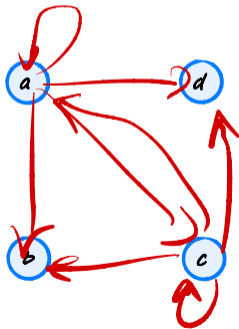
What is the greatest number edges possible in a **directed** graph?

$N$

# Counting Edges

What is the greatest number edges possible in a **directed** graph?

$$4 + 4 + 4 + 4 \\ = 16$$



$$|V|^2$$

## Exercise

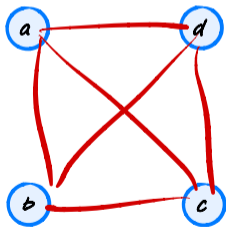
What is the greatest number edges possible in an **undirected** graph?



# Counting Edges

What is the greatest number edges possible in an **undirected** graph?

$$3 + 2 + 1 + 0 \\ = 6$$

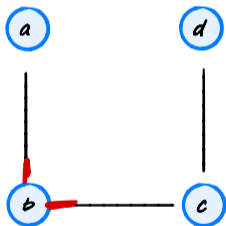


$$\frac{N \times (N-1)}{2} \\ = \binom{N}{2}$$

# Degree

The **degree** of a node in an undirected graph is the number of edges containing that node.

$$\text{deg}(a) = 1$$



$$\text{deg}(d) = 1$$

$$\text{deg}(b) = 2$$

$$\text{deg}(c) = 2$$

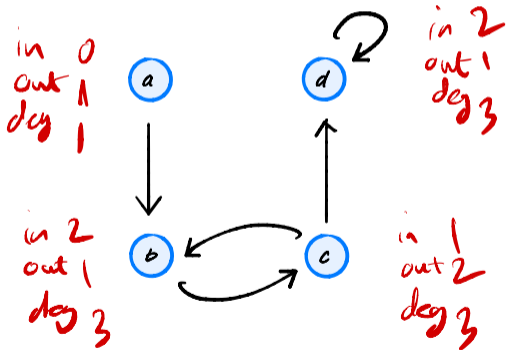
# In-Degree/Out-Degree

The **in-degree** of a node in an directed graph is the number of edges **entering** that node.

The **out-degree** of a node in an directed graph is the number of edges **leaving** that node.

The **degree** of a node in a directed graph is the in-degree + out-degree.

# Examples



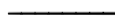
# Neighbors

**Definition:** in an undirected graph, the set of **neighbors** of a node  $u$  is the set of all nodes which share an edge with  $u$ .

$$N(a) = \{b\}$$



$$N(d) = \{c\}$$

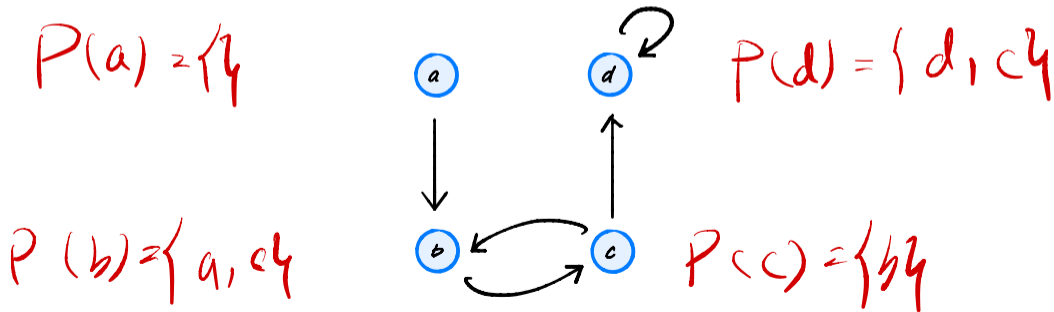


$$N(c) = \{b, d\}$$

$$N(b) = \{a, c\}$$

# Predecessors

**Definition:** in an directed graph, the set of **predecessors** of a node  $u$  is the set of all nodes which are at the **start** of an edge **entering**  $u$ .

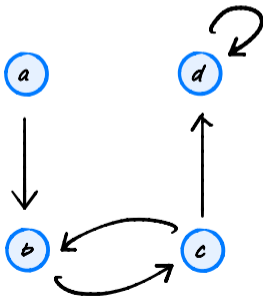


# Successors

**Definition:** in an directed graph, the set of successors of a node  $u$  is the set of all nodes which are at the **end** of an edge **leaving**  $u$ .

$$S(a) = \{b\}$$

$$S(b) = \{c\}$$



$$S(d) = \{d\}$$

$$S(c) = \{b, d\}$$

$(a, b) \in E$   
↑  
Pre- of  $b$

$(a, b) \in E$   
↑  
succ. of  $a$

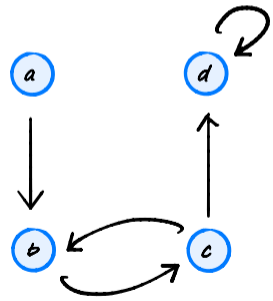
# A Convention

if  $b$  is a successor of  $a$   
 $\Rightarrow (a, b) \in E$

In a directed graph, the **neighbors** of  $u$  are the **successors** of  $u$ .

$$N(a) = \{b\}$$

$$N(b) = \{c\}$$



$$N(d) = \{d\}$$

$$N(c) = \{b, d\}$$



# DSC 40B

## *Theoretical Foundations II*

Lecture 10 | Part 2

**Paths**

## Example

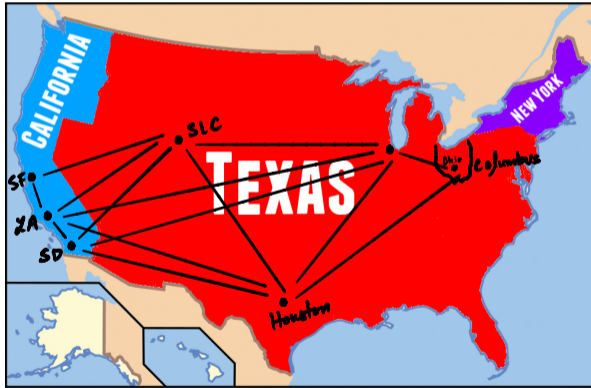


+  
no self-loop

directed  $\equiv$  undirected

- ▶ Consider a graph of direct flights.
- ▶ Each node is an airport.
- ▶ Each edge is a direct flight.
- ▶ Should the graph be directed or undirected?

# Example



# Example

- ▶ Can we get from San Diego to Columbus?
- ▶ Not with a single edge.
- ▶ But with a **path**.



## Definition

A **path** from  $u$  to  $u'$  in a (directed or undirected) graph  $G = (V, E)$  is a sequence of one or more nodes  $u = v_0, v_1, \dots, v_k = u'$  such that there is an edge between each consecutive pair of nodes in the sequence.

# Path Length

**Definition:** The **length** of a path is the number of nodes in the sequence, minus one. Paths of length zero are possible!

# Examples

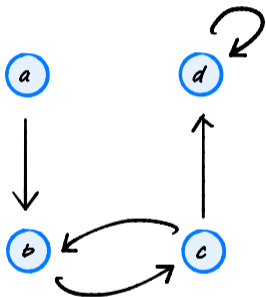
$P_1 = ab$

$P_2 = abc bc$

$P_3 = dd \quad \text{len}(P_3) = 1$

✓

$P_4 = \underbrace{ddd}_{\text{len}(P_4) = 2}$



$acd$

$P_5 = a$

$\text{len}(P_5) = 0$

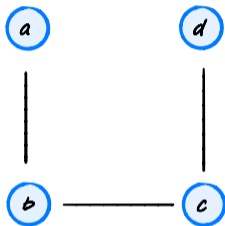
# Examples

✓ a

✗ aa

✓ ab

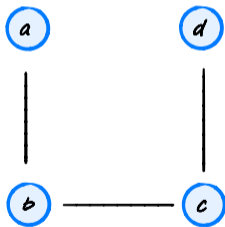
✓ aba





# Note

Paths **can** go through the same node more than once!



# Simple Paths

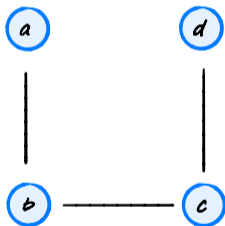
**Definition:** A **simple path** is a path in which every node is unique.

a

ab

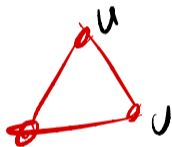
abc

X abcb



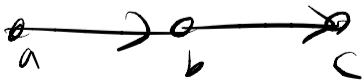
# Reachability

**Definition:** node  $v$  is **reachable** from node  $u$  if there is a path from  $u$  to  $v$ .



# Reachability and Directedness

- ▶ If  $G$  is undirected, reachability is symmetric.
  - ▶ If  $u$  reachable from  $v$ , then  $v$  reachable from  $u$ .
- ▶ If  $G$  is directed, reachability is **not** symmetric.
  - ▶ If  $u$  reachable from  $v$ , then  $v$  may/may not be reachable from  $u$ .



*c is reachable  
from a  
but not vice versa*

## Important Trivia

- ▶ In any graph, any node is **reachable** from **itself**.

$$P = a^v$$

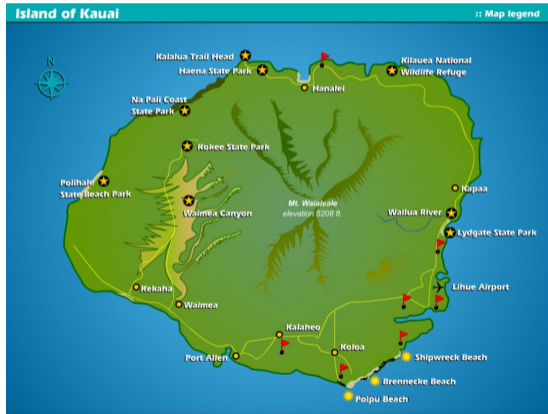
# DSC 40B

## *Theoretical Foundations II*

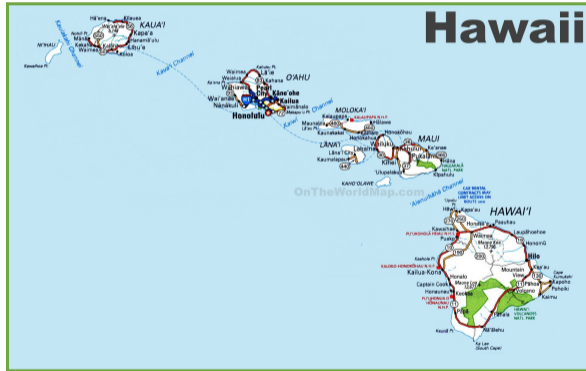
Lecture 10 | Part 3

### **Connected Components**

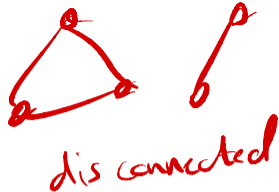
# Example



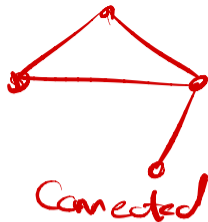
# Example







## Connectedness



A graph is **connected** if every node  $u$  is reachable from every other node  $v$ . Otherwise, it is **disconnected**.

Equivalent: there is a path between every pair of nodes.

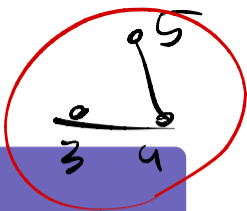
# Connected Components

A **connected component** is a maximally-connected set of nodes.

I.e., if  $G = (V, E)$  is an undirected graph, a connected component is a set  $C \subset V$  such that

- ▶ any pair  $u, u' \in C$  are reachable from one another; and
- ▶ if  $u \in C$  and  $z \notin C$  then  $u$  and  $z$  are not reachable from one another.

3

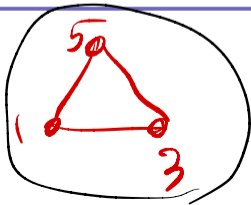
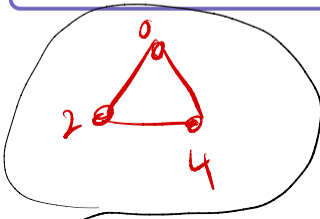


## Exercise

What are the connected components?

$$V = \{0, 1, 2, 3, 4, 5, 6\}$$

$$E = \{(0, 2), (1, 5), (3, 1), (2, 4), (0, 4), (5, 3)\}$$



three connected  
comp.

# Example

What are the connected components?

$$V = \{0, 1, 2, 3, 4, 5, 6\}$$

$$E = \{(0, 2), (1, 5), (3, 1), (2, 4), (0, 4), (5, 3)\}$$

# DSC 40B

## *Theoretical Foundations II*

Lecture 10 | Part 4

### **Adjacency Matrices**

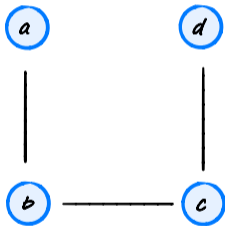
# Representations

- ▶ How do we **store** a graph in a computer's memory?
- ▶ Three approaches:
  1. Adjacency matrices.
  2. Adjacency lists.
  3. "Dictionary of sets"

# Adjacency Matrices

- ▶ Assume nodes are numbered  $0, 1, \dots, |V| - 1$
- ▶ Allocate a  $|V| \times |V|$  (Numpy) array
- ▶ Fill array as follows:
  - ▶  $\text{arr}[i, j] = 1$  if  $(i, j) \in E$
  - ▶  $\text{arr}[i, j] = 0$  if  $(i, j) \notin E$

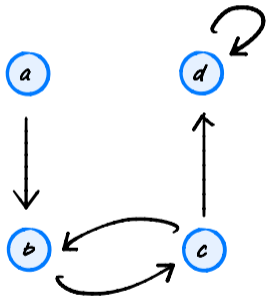
# Example



$$\begin{matrix} & a & b & c & d \\ a & 0 & 1 & 0 & 0 \\ b & 1 & 0 & 1 & 0 \\ c & 0 & 1 & 0 & 1 \\ d & 0 & 0 & 1 & 0 \end{matrix}$$



# Example




	a	b	c	d
a	0	<del>1</del>	0	0
b	<del>0</del>	0	1	0
c	0	1	0	1
d	0	0	0	<del>1</del>

# Observations

- ▶ If  $G$  is undirected, matrix is symmetric. + *diags are zero*
- ▶ If  $G$  is directed, matrix may not be symmetric.

# Time Complexity

operation <sup>3</sup>	code	time
edge query	<u>adj[i,j] == 1</u>	$\Theta(1)$
degree( <i>i</i> )	np.sum(adj[i,:])	$\Theta( V )$ 

---

<sup>3</sup>For undirected graphs

# Space Requirements

- ▶ Uses  $|V|^2$  bits, even if there are very few edges.
- ▶ But most real-world graphs are **sparse**.
  - ▶ They contain many fewer edges than possible.

# Example: Facebook

- ▶ Facebook has 2 billion users.

$$(2 \times 10^9)^2 = 4 \times 10^{18} \text{ bits}$$

$$= 500 \text{ petabits}$$

$$\approx 6500 \text{ years of video at 1080p}$$

$$\approx 60 \text{ copies of the internet as it was in 2000}$$

# Adjacency Matrices and Math

- ▶ Adjacency matrices are useful mathematically.
- ▶ Example:  $(i, j)$  entry of  $A^2$  gives number of hops of length 2 between  $i$  and  $j$ .

# DSC 40B

## *Theoretical Foundations II*

Lecture 10 | Part 5

**Adjacency Lists**

# What's Wrong with Adjacency Matrices?

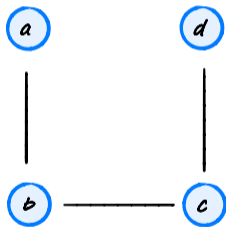
- ▶ Requires  $\Theta(|V|^2)$  storage.
- ▶ Even if the graph has no edges.
- ▶ **Idea:** only store the edges that exist.



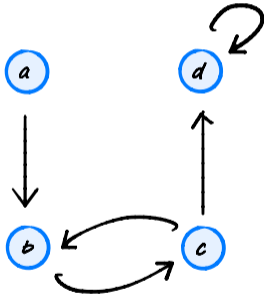
# Adjacency Lists

- ▶ Create a list `adj` containing  $|V|$  lists.
- ▶ `adj[i]` is list containing the neighbors of node  $i$ .

# Example



# Example



# Observations

- ▶ If  $G$  is undirected, each edge appears twice.
- ▶ If  $G$  is directed, each edge appears once.

# Time Complexity

operation <sup>4</sup>	code	time
edge query	<code>j in adj[i]</code>	$\Theta(\text{degree}(i))$
<code>degree(i)</code>	<code>len(adj[i])</code>	$\Theta(1)$

---

<sup>4</sup>For undirected graphs

# Space Requirements

- ▶ Need  $\Theta(|V|)$  space for outer list.
- ▶ Plus  $\Theta(|E|)$  space for inner lists.
- ▶ In total:  $\Theta(|V| + |E|)$  space.

# Example: Facebook

- ▶ Facebook has 2 billion users, 400 billion friendships.
- ▶ If each edge requires 32 bits:

$$\begin{aligned} & (2 \text{ bits} \times 200 \times (2 \text{ billion})) \\ & = 64 \times 400 \times 10^9 \text{ bits} \\ & = 3.2 \text{ terabytes} \\ & = 0.04 \text{ years of HD video} \end{aligned}$$

# DSC 40B

## *Theoretical Foundations II*

Lecture 10 | Part 6

### **Dictionary of Sets**



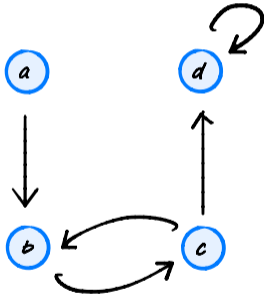
# Tradeoffs

- ▶ Adjacency matrix: fast edge query, lots of space.
- ▶ Adjacency list: slower edge query, space efficient.
- ▶ Can we have the best of both?

# Idea

- ▶ Use **hash tables**.
- ▶ Replace inner edge lists by **sets**.
- ▶ Replace outer list with **dict**.
  - ▶ Doesn't speed things up, but allows nodes to have arbitrary labels.

# Example



# Time Complexity

operation <sup>5</sup>	code	time
edge query	<code>j in adj[i]</code>	$\Theta(1)$ average
<code>degree(i)</code>	<code>len(adj[i])</code>	$\Theta(1)$ average

---

<sup>5</sup>For undirected graphs

# Space Requirements

- ▶ Requires only  $\Theta(E)$ .
- ▶ But there is overhead to using hash tables.

# Dict-of-sets implementation

- ▶ Install with `pip install dsc4ograph`
- ▶ Import with `import dsc4ograph`
- ▶ Docs: <https://eldridgejm.github.io/dsc4ograph/>
- ▶ Source code:  
<https://github.com/eldridgejm/dsc4ograph>
- ▶ Will be used in HW coding problems.