CS-GY 6923: Lecture 4 Continue on Bayesian Perspective, Modeling Language

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Course news

- First written problem set due next Tuesday October 1.
 - I will hold a Zoom office hour for the homework.
 - We will release solutions and go over them in office hours.
- We will release a new lab tomorrow on language modeling.

Recap: probabilistic modeling

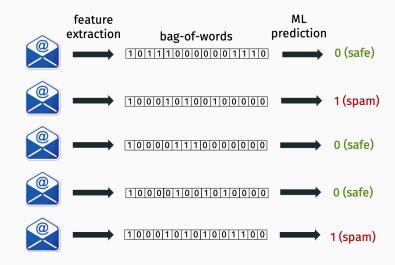
In a $\underline{\text{Bayesian}}$ or $\underline{\text{Probabilistic}}$ approach to machine learning we always start by conjecturing a

probabilistic model

that plausibly could have generated our data.

- The model guides how we make predictions.
- ullet The model typically has unknown parameters $ec{ heta}$ and we try to find the most reasonable parameters based on observed data.

Recap: spam prediction



Recap: email model

Include each word in an email with some fixed probability. That probability will differ depending on whether or not it is a spam or regular email.

Not Spam	<u>Spam</u>
$p_{\text{won},0} = .02$	$p_{won,1} = .1$
$p_{\$,0} = .05$	$p_{\$,1} = .2$
$p_{student,0} = .06$	$p_{student,1} = .01$

Recap: probabilistic model for email

Probabilistic model for (bag-of-words, label) pair (x, y):

- Set y = 0 (not spam) with probability p_0 and y = 1 (spam) with probability $p_1 = 1 p_0$.
 - p_0 is probability an email is not spam (e.g. 99%).
 - p_1 is probability an email is spam (e.g. 1%).
- If y = 0, for each i, set $x_i = 1$ with prob. p_{i0} .
- If y = 1, for each i, set $x_i = 1$ with prob. p_{i1} .

Unknown model parameters:

- p_0, p_1 ,
- $p_{10}, p_{20}, \dots p_{d0}$, one for each of the d vocabulary words.
- $p_{11}, p_{21}, \dots p_{d1}$, one for each of the d vocabulary words.

Recap: parameter estimation

Reasonable way to set parameters:

- Set p_0 and p_1 to the empirical fraction of not spam/spam emails.
- For each word i, set p_{i0} to the empirical probability word i
 appears in a non-spam email.
- For each word i, set p_{i1} to the empirical probability word i
 appears in a <u>spam</u> email.

One with modeling on to prediction

Probability review

- **Probability:** p(x) the probability event x happens.
- Joint probability: p(x,y) the probability that event x and event y happen.
- Conditional Probability $p(x \mid y)$ the probability x happens given that y happens.

$$p(x|y) = \frac{p(y|x)p(x)}{p(y)}$$

Classification rule

Given unlabeled input (\mathbf{w} ,....), choose the label $y \in \{0,1\}$ which is most likely given the data. Recall $\mathbf{w} = [0,0,1,\ldots,1,0]$.

Classification rule: maximum a posterior (MAP) estimate.

Step 1. Compute:

- $p(y = 0 \mid \mathbf{w})$: prob. y = 0 given observed data vector \mathbf{w} .
- $p(y = 1 \mid \mathbf{w})$: prob. y = 1 given observed data vector \mathbf{w} .

Step 2. Output: 0 or 1 depending on which probability is larger.

 $p(y = 0 \mid \mathbf{w})$ and $p(y = 1 \mid \mathbf{w})$ are called **posterior** probabilities.

Evaluating the posterior

How to compute the posterior? Bayes rule!

$$p(y=0 \mid \mathbf{w}) = \frac{p(\mathbf{w} \mid y=0)p(y=0)}{p(\mathbf{w})}$$
(1)

$$posterior = \frac{likelihood \times prior}{evidence}$$
 (2)

- **Prior:** Probability in class 0 prior to seeing any data.
- Posterior: Probability in class 0 <u>after</u> seeing the data.

Evaluating the posterior

Goal is to determine which is larger:

$$p(y = 0 \mid \mathbf{w}) = \frac{p(\mathbf{w} \mid y = 0)p(y = 0)}{p(\mathbf{w})}$$
 vs.
$$p(y = 1 \mid \mathbf{w}) = \frac{p(\mathbf{w} \mid y = 1)p(y = 1)}{p(\mathbf{w})}$$

- We can ignore the evidence $p(\mathbf{w})$ since it is the same for both sides!
- p(y=0) and p(y=1) already known (computed from training data). These are our computed parameters p_0 , p_1 .
- $p(\mathbf{w} \mid y = 0) = ? p(\mathbf{w} \mid y = 1) = ?$

Evaluating the posterior

Consider the example $\mathbf{w} = [0, 1, 1, 0, 0, 0, 1, 0].$

Recall that, under our model, index i is 1 with probability p_{i0} if we are not spam, and 1 with probability p_{i1} if we are spam .

$$p(\mathbf{w} \mid y = 0) =$$

$$p(\mathbf{w} \mid y = 1) =$$

Naive bayes classifier

Training/Modeling: Use existing data to compute:

- $p_0 = p(y = 0), p_1 = p(y = 1)$
- For all *i* compute:
 - $p_{i0} = p(w_i = 1 \mid y = 0)$ and $(1 p_{i0}) = p(w_i = 0 \mid y = 0)$
 - $p_{i1} = p(w_i = 1 \mid y = 1)$ and $(1 p_{i1}) = p(w_i = 0 \mid y = 1)$

Prediction:

- For new input w:
 - Compute $p(\mathbf{w} \mid y = 0) = \prod_{i} p(w_i \mid y = 0)$
 - Compute $p(\mathbf{w} \mid y = 1) = \prod_{i} p(w_i \mid y = 1)$
- Return y = 0 if $p(\mathbf{w} \mid y = 0) \cdot p(y = 0) \ge p(\mathbf{w} \mid y = 1) \cdot p(y = 1)$
- Return y = 1 otherwise

Other applications of the bayesian perspective on regression

Bayesian regression

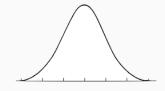
The Bayesian view offers an interesting alternative perspective on many machine learning techniques.

Example: Linear Regression.

Probabilistic model:

$$y = \langle \mathbf{x}, \boldsymbol{\beta} \rangle + \eta$$

where the η drawn from $N(0, \sigma^2)$ is random Gaussian noise.



$$Pr(\eta = z) \sim$$

The symbol \sim means "is proportional to".

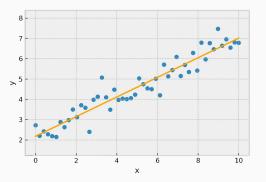
Illustration

Example: Linear Regression.

Probabilistic model:

$$y = \langle \mathbf{x}, \boldsymbol{\beta} \rangle + \eta$$

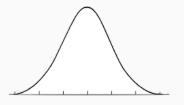
where the η drawn from $N(0, \sigma^2)$ is **random Gaussian noise**. The noise is <u>independent</u> for different inputs $\mathbf{x}_1, \dots, \mathbf{x}_n$.



Gaussian distribution refresher

Names for same thing: Normal distribution, Gaussian distribution, bell curve.

Parameterized by mean μ and variance σ^2 .

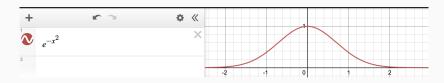


 η is a continuous random variable, so it has a <u>probability density function</u> $p(\eta)$ with $\int_{-\infty}^{\infty} p(\eta) d\eta = 1$

$$p(\eta) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{1}{2}(\frac{\eta-\mu}{\sigma})^2}$$

Gaussian distribution refresher

The important thing to remember is that the PDF falls off exponentially as we move further from the mean.



The normalizing constant in front 1/2, etc. don't matter so much.

Bayesian regression

How should we select β for our model?

Also use a Bayesian approach!

First thought: choose β to maximize:

$$\mathsf{posterior} = \mathsf{Pr}(\boldsymbol{\beta} \mid \mathbf{X}, \mathbf{y}) = \frac{\mathsf{Pr}(\mathbf{X}, \mathbf{y} \mid \boldsymbol{\beta}) \, \mathsf{Pr}(\boldsymbol{\beta})}{\mathsf{Pr}(\mathbf{X}, \mathbf{y})} = \frac{\mathsf{likelihood} \times \mathsf{prior}}{\mathsf{evidence}}.$$

But in this case, we don't have a prior – no values of β are inherently more likely than others.

Choose β to maximize just the likelihood:

$$\frac{\Pr(\mathbf{X}, \mathbf{y} \mid \beta) \Pr(\beta)}{\Pr(\mathbf{X}, \mathbf{y})} = \frac{\mathsf{likelihood} \times \mathsf{prior}}{\mathsf{evidence}}.$$

This is called the **maximum likelihood estimate**.

Fixed design linear regression

- Often we think of X as fixed and deterministic, and only y is generated at random in the model. This is called the <u>fixed</u> <u>design</u> setting.
- We can also consider a <u>randomized design</u> setting, but it is slightly more complicated.
- In the fixed design setting our task of maximizing $\Pr(\mathbf{X}, \mathbf{y} \mid \beta)$ simplifies to maximizing

$$\max_{\boldsymbol{\beta}} \Pr(\mathbf{y} \mid \boldsymbol{\beta})$$

Maximum likelihood estimate

Data:

$$\mathbf{X} = \begin{bmatrix} - & \mathbf{x}_1 & - \\ - & \mathbf{x}_2 & - \\ & \vdots & \\ - & \mathbf{x}_n & - \end{bmatrix} \qquad \qquad \mathbf{y} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$$

Model: $y_i = \langle \mathbf{x}_i, \boldsymbol{\beta} \rangle + \eta_i$ where $p(\eta_i = z) \sim e^{-z^2/2\sigma^2}$ and η_1, \dots, η_n are independent.

Exercise:

$$\mathsf{Pr}(\mathbf{y}\mid oldsymbol{eta}) \sim$$

Log likelihood

Easier to work with the log likelihood:

$$\begin{split} \arg\max_{\boldsymbol{\beta}} \Pr(\mathbf{X}, \mathbf{y} \mid \boldsymbol{\beta}) &= \arg\max_{\boldsymbol{\beta}} \prod_{i=1}^n e^{-(y_i - \langle \mathbf{x}_i, \boldsymbol{\beta} \rangle)^2/2\sigma^2} \\ &= \arg\max_{\boldsymbol{\beta}} \log \left(\prod_{i=1}^n e^{-(y_i - \langle \mathbf{x}_i, \boldsymbol{\beta} \rangle)^2/2\sigma^2} \right) \\ &= \arg\max_{\boldsymbol{\beta}} \sum_{i=1}^n -(y_i - \langle \mathbf{x}_i, \boldsymbol{\beta} \rangle)^2/2\sigma^2 \\ &= \arg\min_{\boldsymbol{\beta}} \sum_{i=1}^n (y_i - \langle \mathbf{x}_i, \boldsymbol{\beta} \rangle)^2. \end{split}$$

Maximum likelihood estimator

Conclusion: Choose β to minimize:

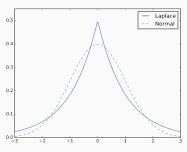
$$\sum_{i=1}^{n} (y_i - \langle \mathbf{x}_i, \boldsymbol{\beta} \rangle)^2 = \|\mathbf{y} - \mathbf{X}\boldsymbol{\beta}\|_2^2.$$

This is a completely different justification for squared loss!

Minimizing the ℓ_2 loss is "optimal" when you assume your data follows a linear model with i.i.d. Gaussian noise.

Bayesian regression

If we had modeled our noise η as Laplace noise, we would have found that minimizing $\|\mathbf{y} - \mathbf{X}\boldsymbol{\beta}\|_1$ was optimal.



$$Pr(\eta = z) \sim$$

Laplace noise has "heavier tails", meaning that it results in more outliers.

This is a completely different justification for ℓ_1 loss.

- We can add another layer of probabilistic modeling by also assuming β is random and comes from some distribution, which encodes our prior belief on what the parameters are.
- Recall Maximum a posteriori (MAP estimation):

$$Pr(\beta \mid \mathbf{X}, \mathbf{y}) = \frac{Pr(\mathbf{X}, \mathbf{y} \mid \beta) Pr(\beta)}{Pr(\mathbf{X}, \mathbf{y})}.$$

- Assume values in $\beta = [\beta_1, \dots, \beta_d]$ come from some distribution.
- What is a common model?

- Common model: Each β_i drawn from $N(0, \gamma^2)$, i.e. normally distributed, independent.
- Encodes a belief that we are unlikely to see models with very large coefficients.

Goal: choose β to maximize:

$$Pr(\beta \mid \mathbf{X}, \mathbf{y}) = \frac{Pr(\mathbf{X}, \mathbf{y} \mid \beta) Pr(\beta)}{Pr(\mathbf{X}, \mathbf{y})}.$$

Goal: choose β to maximize:

$$\mathsf{Pr}(\boldsymbol{\beta}\mid \mathbf{X},\mathbf{y}) = \frac{\mathsf{Pr}(\mathbf{X},\mathbf{y}\mid \boldsymbol{\beta})\,\mathsf{Pr}(\boldsymbol{\beta})}{\mathsf{Pr}(\mathbf{X},\mathbf{y})}.$$

- We can still ignore the "evidence" term Pr(X, y) since it is a constant that does not depend on β .
- $Pr(\beta) = Pr(\beta_1) \cdot Pr(\beta_2) \cdot \ldots \cdot Pr(\beta_d)$
- If each β_i drawn from $N(0, \gamma^2)$, $Pr(\beta) \sim$?

Easier to work with the log likelihood:

$$\begin{split} & \operatorname*{arg\,max} \Pr(\mathbf{X}, \mathbf{y} \mid \boldsymbol{\beta}) \cdot \Pr(\boldsymbol{\beta}) \\ & = \operatorname*{arg\,max} \prod_{i=1}^n e^{-(y_i - \langle \mathbf{x}_i, \boldsymbol{\beta} \rangle)^2 / 2\sigma^2} \cdot \prod_{i=1}^n e^{-(\beta_i)^2 / 2\gamma^2} \\ & = \operatorname*{arg\,max} \sum_{i=1}^n -(y_i - \langle \mathbf{x}_i, \boldsymbol{\beta} \rangle)^2 / 2\sigma^2 + \sum_{i=1}^d -(\beta_i)^2 / 2\gamma^2 \\ & = \operatorname*{arg\,min} \sum_{\beta} \sum_{i=1}^n (y_i - \langle \mathbf{x}_i, \boldsymbol{\beta} \rangle)^2 + \frac{\sigma^2}{\gamma^2} \sum_{i=1}^d (\beta_i)^2 \end{split}$$

Choose $\boldsymbol{\beta}$ to minimize $\|\mathbf{y} - \mathbf{X}\boldsymbol{\beta}\|_2^2 + \frac{\sigma^2}{\gamma^2}\|\boldsymbol{\beta}\|_2^2$.

Completely different justification for ridge regularization!

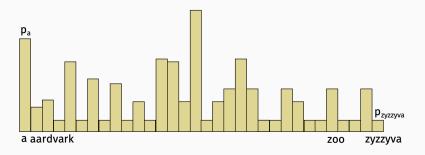
Test your intuition: What modeling assumption justifies LASSO regularization: $\min \|\mathbf{y} - \mathbf{X}\boldsymbol{\beta}\|_2^2 + \lambda \|\boldsymbol{\beta}\|_1$?

Modeling language

Generative ML

Key idea behind generative ML:

- Build a very good probabilistic model for your data.
- Use that model to generate realistic looking new data.



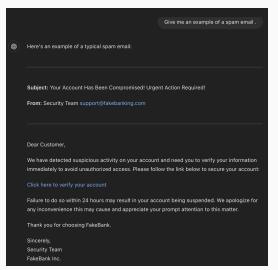
Example

Key idea behind generative ML: Build a very good probabilistic model for your data. Use that model to generate realistic looking new data.

Email example from our model: Keeps retaining in astro associated to no garden superconducting whistleblower on effusion eigenvalue jobs worker for car shortlist villa depictions fitness the easter veto devices expressed secondary user metal this administrative the do of to struct coffee online cde the open through requirement stamps you job g thus drop stations.

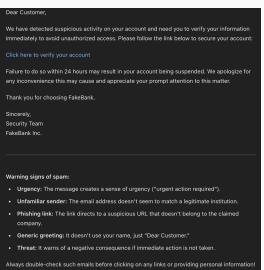
Language modeling

How do we go from this to something more like what modern models can produce?



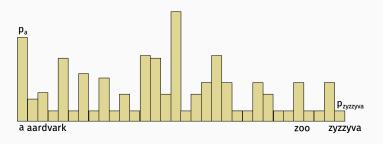
Language modeling

How do we go from jumbled words to something more like what modern models can produce?



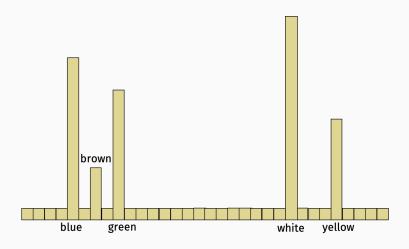
Main issue: Our model lacks context!

The color of the dress is _____.



Main issue: Our model lacks context!

The color of the dress is _____.



Key idea: Distribution that a word is chosen from should depend on previous words in the sentence/paragraph.

Consider generating a sentence with words x_1, x_2, \ldots, x_n .

- Initialize the first word x_1 of the sentence (e.g. at random).
- Choose x_2 based on x_1 .
- Choose x_3 based on x_1, x_2, \dots

Concretely, set $x_i = w$ with probability:

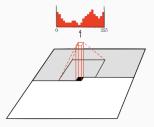
$$P(x_i = w \mid x_{i-1}, x_{i-2}, \dots, x_1).$$

Autoregressive model's generate text in order.

- How most humans write sentences, emails, short text.
- How the latest modern language models write text (e.g. the GPT family of models.)

This is not the only approach to generative modeling, but it is one that works fairly well in practice, especially for text.

Can also be used e.g. for images, but no longer state of the art.



Limited lookback

Key idea: Distribution that a word is chosen from should depend on previous k words in the sentence/paragraph. k is a parameter that controls model complexity.

Consider generating a sentence with words x_1, x_2, \ldots, x_n .

- Initialize the first k word x_1, \ldots, x_k of the sentence (e.g. at random).
- Choose x_{k+1} based on x_1, \ldots, x_k .
- Choose x_{k+2} based on x_2, \ldots, x_{k+1} .
- Choose x_{k+3} based on x_3, \ldots, x_{k+2} .
- ...

Set $x_i = w$ with probability:

$$P(x_i = w \mid x_{i-1}, x_{i-2}, \dots, x_{i-k}).$$

Limited lookback

Set $x_i = w$ with probability:

$$P(x_i = w \mid x_{i-k}, \dots, x_{i-2}, x_{i-1}).$$

This probability can be tractably estimate from our data!

It is exactly the same as the probability of observing the k+1-gram $[x_{i-k},\ldots,x_{i-2},x_{i-1},w]$.

Training:

ullet For corpus of text, collect all k+1-grams and record their frequency.

Prediction:

• At step i, sample from the subset of k+1 grams starting with $[x_{i-k}, \ldots, x_{i-2}, x_{i-1}]$, with probability proportional to their frequency.

Example

The color of the dress is _____.

• Reasonable completions for k = 2:

• Reasonable completions for k = 5:

Lab 3

Credit to Raphael Meyer who was a Ph.D. student at CSE Tandon, currently a postdoc at Caltech.



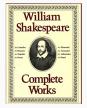
Lab 3

Train model on free books from Project Gutenberg.









• Evaluate effect of changing *k*. Tradeoff between better performance and more "copying" from the course text.

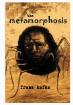
Virtue itself of vice must pardon beg, Yea, curb and woo for leave to do him good, She shall undo her credit with the judge, or own great place, Could fetch your brother from the angry law; do no stain to your own souls so blind That you will clear yourself from all suspense.

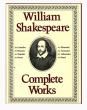
Lab 3

Train model on free books from Project Gutenberg.









• Evaluate effect of changing k. Tradeoff between better performance and more "copying" from the source text.

During this time, Madame Morrel had told her all,—'Giovanni,' said she, 'you should have brought this child with you; we would have replaced the parents it has lost, have called it Benedetto, and then, in a loyal duel, and not in Arabia, and in France eternal friendships are as rare as the custom of doing when saying "Yes." "Good; he accepts," said Monte Cristo.